



BINARY PYTHON

introducing native code

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Hi I'm Armin

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(where stores are closed on sundays)



Rotteneegg

Gemeinde St. Gotthard

Windpassing



SENTRY

I <3 AND BUILD OPEN SOURCE

Werkzeug, Jinja, Flask, Sentry, ...

OUR HEART BEATS FOR

Python

But we also have other
things we need to
interface with ...

C // C++ // RUST

WHY DO WE HAVE
NATIVE CODE?

SPEED

Functionality

NECESSITY

IMPORTING NATIVE MODULES



Import System

- ★ `package/mylib.so`
- ★ `package/mylib.pyd`
- ★ `package/mylib.dylib`

Local Development

- ★ `lib/lib.c -> package/_lib.so`
- ★ `python setup.py build`
- ★ `pip install --editable . -v`

Build for Distribution

★ `lib/lib.c -> build/.../_lib.so`

★ `python setup.py bdist_wheel`

WHY HANDROLL



MANY SYSTEMS

MANY DEVELOPERS

RUN "EVERYWHERE"

that rules out most already
existing solutions. SAD

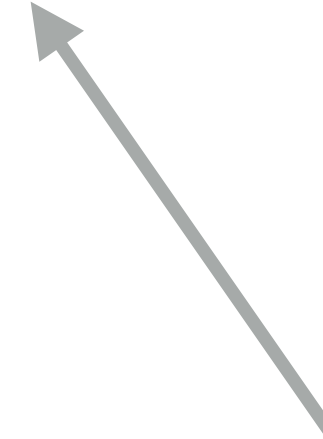
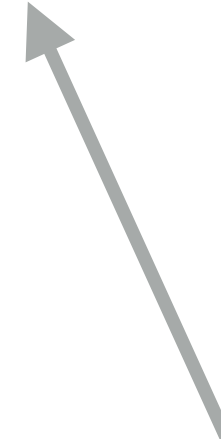
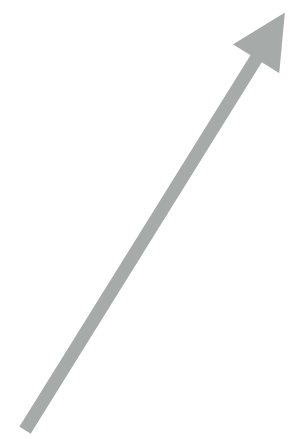
DISTRIBUTING



Python Wheels

- ★ .py files are portable
- ★ .pyc files are generated on install
- ★ wheel is largely universal

sentry-8.12.0-py27-none-any.whl



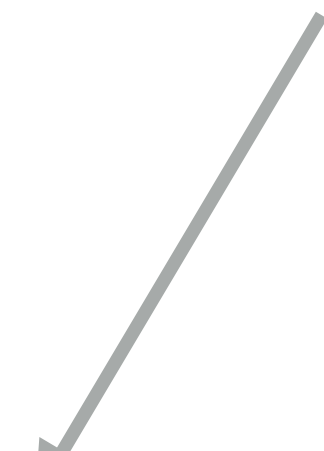
Package Name

Version

Python Tag

ABI Tag

Platform Tag



Flask-0.12-py2.py3-none-any.whl

Binaries

- ★ Platform Specific
- ★ libc specific :(
- ★ might link against system libraries
- ★ typically cannot compile on installation time

Binary Wheels

- ★ “easy” on OS X
- ★ trivial on Windows
- ★ limited support on Linux (*manylinux1*)

symsynd-1.3.0-cp27-none-manylinux1_x86_64.whl

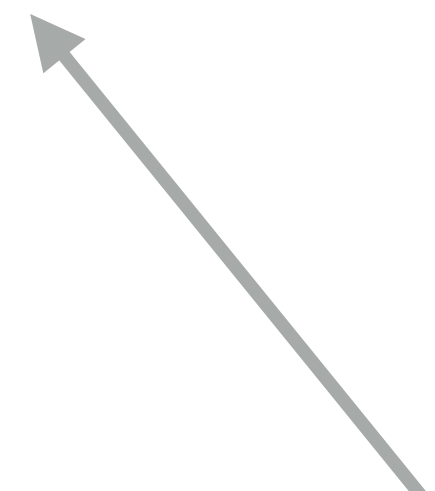
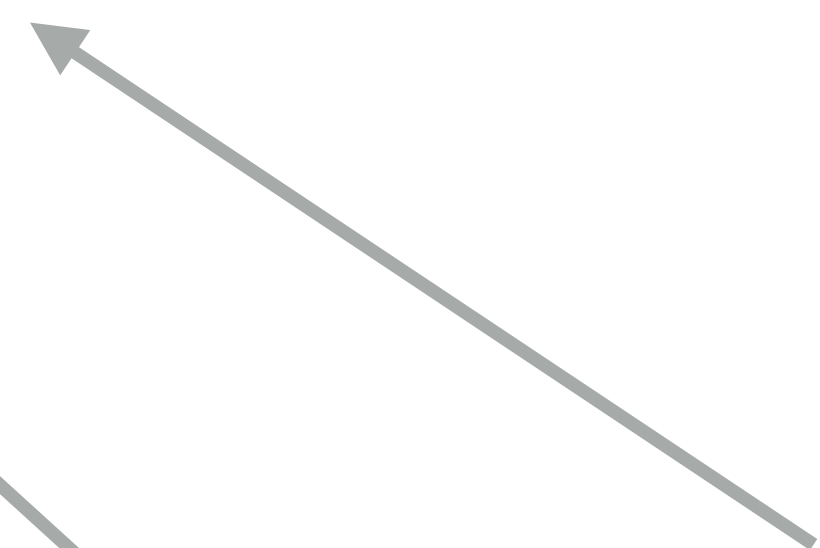
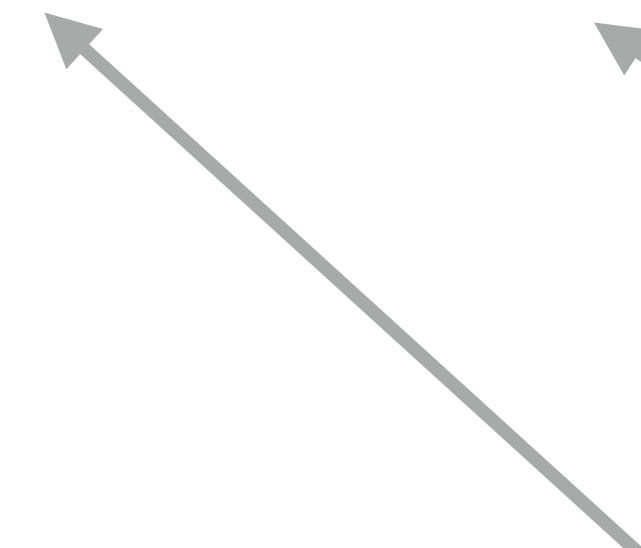
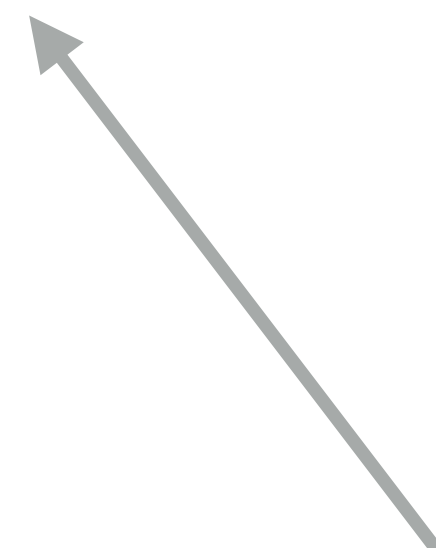
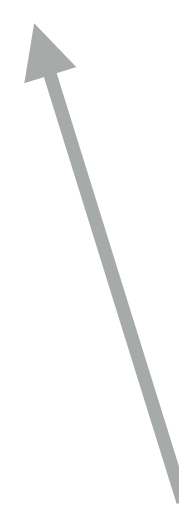
Package Name

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Python Tag

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Pillow-4.0.0-cp36-cp36m-manylinux1_x86_64.whl

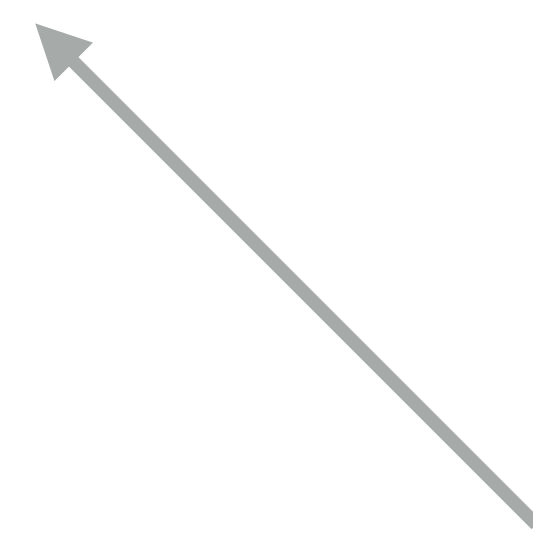
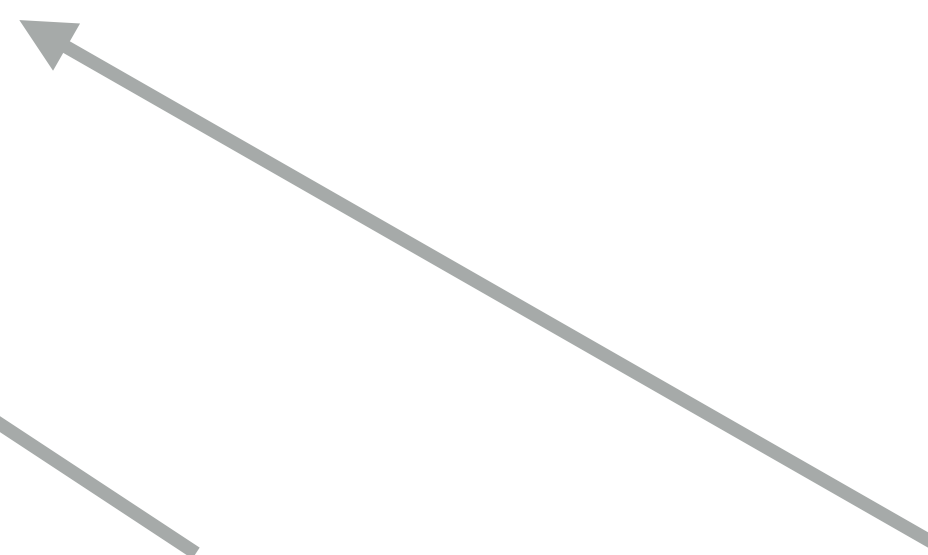
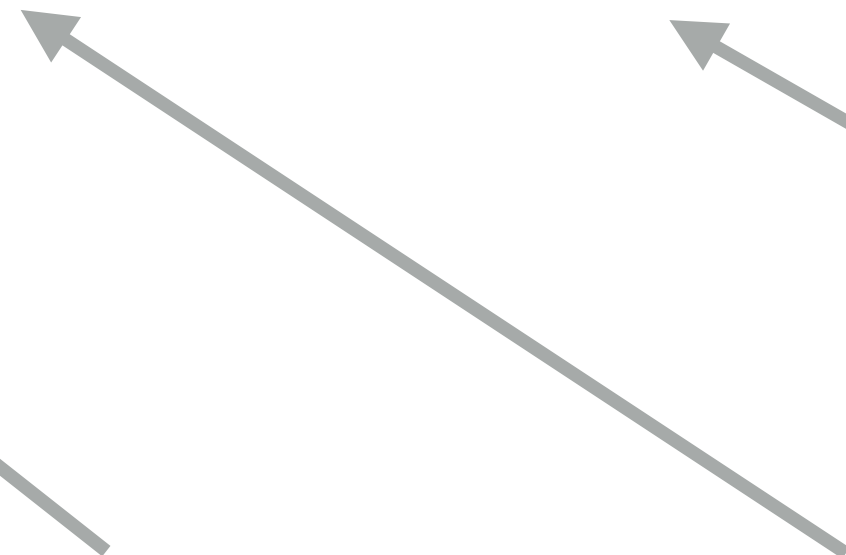
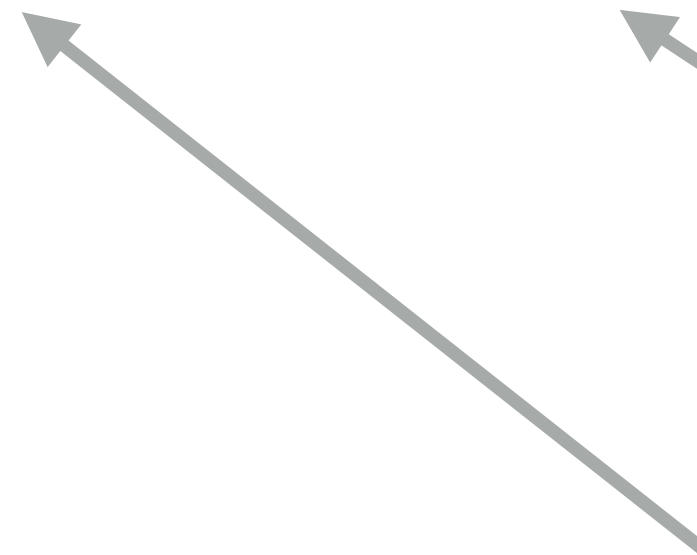
Package Name

Version

Python Tag

ABI Tag

Platform Tag



ALL THE TAGS



Python Tag

- ★ any python version
- ★ any 2.x / 3.x version
- ★ a specific version
- ★ a specific Python implementation
(*cpython, pypy, ...*)

ABI Tag

- ★ the Python Interpreter ABI version
(eg: UC2 vs UC4)

Platform Tag

- ★ identifies the platform
- ★ eg: 32bit Intel OS X, x86_64
- ★ platform can be complex.
(eg: *manylinux1_x86_64*)

WTF IS MANYLINUX1?



linux binary compatibility
is fraking terrible

manylinux1

- ★ compile on super old CentOS version
- ★ do not link against fancy libraries
- ★ only use old C++ compilers if at all
- ★ static link all the things you can

where to get ancient CentOS?



docker

FEWER DIMENSIONS



Pillow-4.0.0-cp36-cp36m-manylinux1_x86_64.whl

Python 2 builds:

Versions: 2.7

ABI: cpm + cpmu

Platforms: OS X + 2 Linux

Total: $1 \times 2 \times 3 = \mathbf{6}$

Python 3 builds:

Versions: 3.3 + 3.4 + 3.5 + 3.6 + 3.7

ABI: cpm

Platforms: OS X + 2 Linux

Total: $5 \times 1 \times 3 = \mathbf{15}$

21 BUILDS!!!

that's a lot of wheels. SAD

Can we kill tags?

- ★ Python version tag: write Python 2.x and 3.x source compatible code
- ★ ABI Tag: do not link against libpython
- ★ Platform Tag: we can't do anything about this one :(

path to success:

- do not link to libpython
- use cffi
- 2.x/3.x compatible sources
- fuck around with setuptools

SETUPTOOLS



```
import os
from distutils.command.build_py import build_py
from distutils.command.build_ext import build_ext

PACKAGE = 'mypackage'

class CustomBuildPy(build_py):
    def run(self):
        build_py.run(self)
        build_mylib(os.path.join(self.build_lib, *PACKAGE.split('.')))

class CustomBuildExt(build_ext):
    def run(self):
        build_ext.run(self)
        if self.inplace:
            build_py = self.get_finalized_command('build_py')
            build_mylib(build_py.get_package_dir(PACKAGE))
```

```
from wheel.bdist_wheel import bdist_wheel

class CustomBdistWheel(bdist_wheel):
    def get_tag(self):
        rv = bdist_wheel.get_tag(self)
        return ('py2.py3', 'none') + rv[2:]
```

```
from setuptools import setup
```

```
setup(  
    ...  
    cffi_modules=['build.py:my_ffi'],  
    install_requires=['cffi>=1.0.0'],  
    setup_requires=['cffi>=1.0.0'],  
    cmdclass={  
        'build_ext': CustomBuildExt,  
        'build_py': CustomBuildPy,  
        'bdist_wheel': CustomBdistWheel,  
    }  
)
```

BUILD MY LIB



```
import os
import sys
import shutil
import subprocess
```

```
EXT = sys.platform == 'darwin' and '.dylib' or '.so'
```

```
def build_mylib(base_path):
    lib_path = os.path.join(base_path, '_nativelib.so')
    here = os.path.abspath(os.path.dirname(__file__))
    cmdline = ['make', 'build-ext']
    rv = subprocess.Popen(cmdline, cwd=here).wait()
    if rv != 0:
        sys.exit(rv)
    src_path = os.path.join(here, 'target', 'release', 'libnativelib' + EXT)
    if os.path.isfile(src_path):
        shutil.copy2(src_path, lib_path)
```

The diagram features two callout boxes with black borders and white backgrounds. The first callout, labeled 'build command', is positioned above the 'cmdline' list in the code and has an arrow pointing to the 'make' and 'build-ext' elements. The second callout, labeled 'build output path', is positioned to the right of the code and has an arrow pointing to the 'src_path' variable.

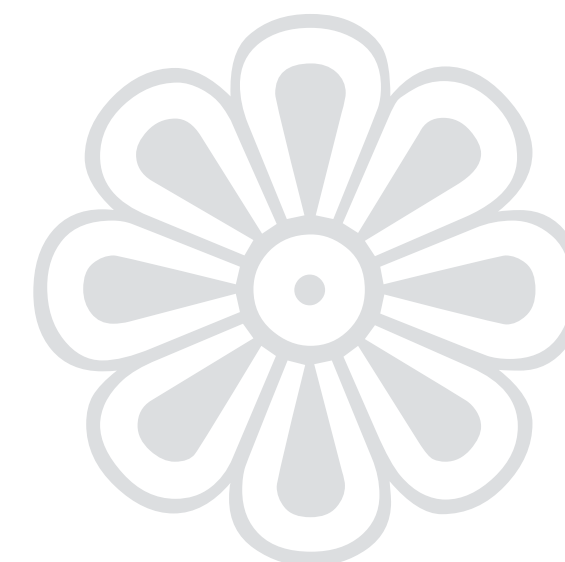
develop:

```
pip install --editable . -v
```

build-ext:

```
cargo build --release
```


CFFI (*build.py*)



header only

```
import sys
import subprocess
from cffi import FFI

def _to_source(x):
    if sys.version_info >= (3, 0) and isinstance(x, bytes):
        x = x.decode('utf-8')
    return x
```

good for typedefs

```
my_ffi = FFI()
my_ffi.cdef(_to_source(subprocess.Popen([
    'cc', '-E', '-DPYTHON_HEADER',
    'mynativelib/mynativelib.h'],
    stdout=subprocess.PIPE).communicate()[0]))
my_ffi.set_source('mypackage._nativelib', None)
```

with source compilation

```
my_ffi = FFI()
my_ffi.cdef(_to_source(subprocess.Popen([
    'cc', '-E', '-DPYTHON_HEADER',
    'mynativelib/mynativelib.h'],
    stdout=subprocess.PIPE).communicate()[0]))

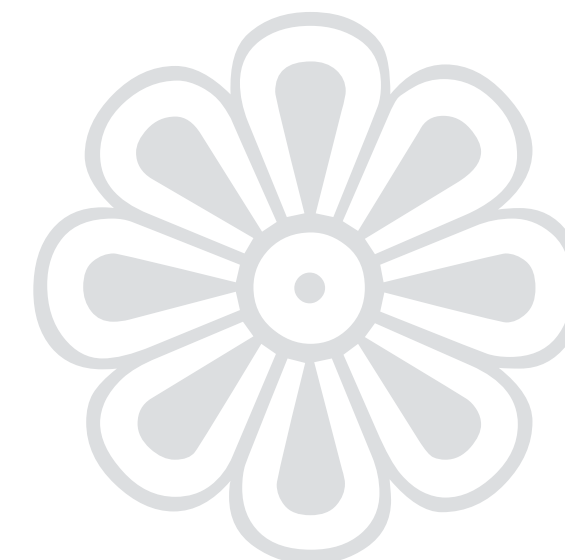
with open('mynativelib/mynativelib.cpp', 'rb') as source:
    my_ffi.set_source(
        'mypackage/_nativelib',
        _to_source(source.read()),
        include_dirs=['mynativelib'],
        extra_compile_args=['-std=c++11'],
        source_extension='.cpp'
    )
```

GITIGNORE



```
mypackage/_nativelib.py  
mypackage/*.so  
mypackage/*.dylib  
build  
dist  
*.pyc  
*.egg-info
```

WRAPPING WITH CFFI



```
from ._nativelib import ffi as _ffi

_lib = _ffi.dlopen(os.path.join(
    os.path.dirname(__file__), '_nativelib.so'))
_lib.mylib_global_init_if_needed()

class MyObject(object):

    def __init__(self):
        self._ptr = _lib.my_object_new()

    def __del__(self):
        if self._ptr:
            _lib.my_object_free(self._ptr)
            self._ptr = None
```

```
from .nativelib import ffi as _ffi, lib as _lib
```

```
_lib.mylib_global_init_if_needed()
```

```
class MyObject(object):
```

```
    def __init__(self):
```

```
        self._ptr = _lib.my_object_new()
```

```
    def __del__(self):
```

```
        if self._ptr:
```

```
            _lib.my_object_free(self._ptr)
```

```
            self._ptr = None
```


now for building. SO SAD

BASICS



```
$ pip install wheel  
$ python setup.py bdist_wheel
```



docker

USEFUL IMAGES



For Python in General

- ★ quay.io/pypa/manylinux1_i686
- ★ quay.io/pypa/manylinux1_x86_64

Things of note

- ★ It's an ancient CentOS (*for instance it has no SNI Support*)
- ★ 32bit builds on on 64bit Docker typically. Use the `linux32` command
- ★ Dockerfile allows you to "cache" steps

How we do it

- ★ travis all the things
- ★ upload artifacts to github releases
- ★ download from there an upload to pypi with twine

what about macOS?

build on travis / locally

- ★ travis better because you can build on old macOS for higher portability
- ★ you can find old SDKs on github!
- ★ Use `MACOS_DEPLOYMENT_TARGET`

```
WHEEL_OPTIONS=  
if [ `uname` == "Darwin" ]; then  
    WHEEL_OPTIONS="--plat-name=macosx-10.10-intel"  
fi  
python setup.py bdist_wheel $WHEEL_OPTIONS
```

PATTERNS



LIBRARY DESIGN

```
#ifndef MYLIB_H_INCLUDED
#define MYLIB_H_INCLUDED

#ifdef __cplusplus
extern "C" {
#endif

typedef void mylib_type_t;

mylib_type_t *mylib_type_new(void);
void mylib_type_free(mylib_type_t *self);

#ifdef __cplusplus
}
#endif

#endif
```

```
#include "mylib.h"

class Type {
    Type();
    ~Type();
};

mylib_type_t *mylib_type_new()
{
    Type *rv = new Type();
    (mylib_type_t *)rv;
}

void mylib_type_free(mylib_type_t *self)
{
    if (self) {
        Type *t = (Type *)self;
        delete t;
    }
}
```

Error handling


```
typedef struct mylib_error_t {
    int code;
    char *msg;
};

void mylib_error_free(mylib_error_t *err)
{
    if (err) {
        free(err->msg);
        free(err);
    }
}
```

```
int mylib_do_stuff(int a, int b, mylib_error_t **err_out)
{
    if (a + b > 255) {
        mylib_error_t *err = malloc(mylib_error_t);
        err->msg = strdup("Adding those chars overflows");
        err->code = MYLIB_CHAR_OVERFLOW;
        *err_out = err;
        return -1;
    }

    return a + b;
}
```

```
special_errors = {}
```

```
def invoke_with_exc(func, *args):  
    err = _ffi.new('mylib_error_t **')  
    try:  
        rv = func(*(args + (err,)))  
        if not err[0]:  
            return rv  
        cls = special_errors.get(err[0].code, RuntimeError)  
        raise cls(_ffi.string(err[0].msg).decode('utf-8', 'replace'))  
    finally:  
        if err[0]:  
            _lib.mylib_error_free(err[0])
```

```
try:  
    rv = invoke_with_exc(_lib.mylib_do_stuff, arg1, arg2)  
except DefaultError as e:  
    print 'An error happened: %s' % e  
else:  
    print 'The result is %r' % rv
```

CONCLUSIONS



how painful is it?

it's pretty bad. SAD

but when it works it keeps
working. LOVE IT

what do we use it for?

C/C++

Native Symbolication

Rust

Javascript Source Maps

Q&A



```
def rustcall(func, *args):
    err = _ffi.new('lsm_error_t *')
    rv = func(*(args + (err,)))
    if not err[0].failed:
        return rv
    try:
        cls = special_errors.get(err[0].code, SourceMapError)
        exc = cls(_ffi.string(err[0].message).decode('utf-8', 'replace'))
    finally:
        _lib.lsm_buffer_free(err[0].message)
    raise exc
```

```
use std::mem;
use std::panic;

fn silent_panic_handler(_pi: &panic::PanicInfo) {
    /* don't do anything here */
}

#[no_mangle]
pub unsafe extern "C" fn mylib_init() {
    panic::set_hook(Box::new(silent_panic_handler));
}
```

```
unsafe fn set_err(err: Error, err_out: *mut CError) {  
    if err_out.is_null() {  
        return;  
    }  
    let s = format!("{}", err);  
    (*err_out).message = Box::into_raw(s.into_boxed_str()) as *mut u8;  
    (*err_out).code = err.get_error_code();  
    (*err_out).failed = 1;  
}
```



```
unsafe fn landingpad<F: FnOnce() -> Result<T> + panic::UnwindSafe, T>(
    f: F, err_out: *mut CError) -> T
{
    if let Ok(rv) = panic::catch_unwind(f) {
        rv.map_err(|err| set_err(err, err_out)).unwrap_or(mem::zeroed())
    } else {
        set_err(ErrorKind::InternalError.into(), err_out);
        mem::zeroed()
    }
}
```

```
macro_rules! export (
    ($n:ident($($an:ident: $aty:ty),*) -> Result<$rv:ty> $body:block) => (
        #[no_mangle]
        pub unsafe extern "C" fn $n($($an: $aty,)* err: *mut CError) -> $rv
        {
            landingpad(|| $body, err)
        }
    );
);
```

```
export!(lsm_view_dump_memdb(
    view: *mut View, len_out: *mut c_uint, with_source_contents: c_int,
    with_names: c_int) -> Result<*mut u8>
{
    let memdb = (*view).dump_memdb(DumpOptions {
        with_source_contents: with_source_contents != 0,
        with_names: with_names != 0,
    })?;
    *len_out = memdb.len() as c_uint;
    Ok(Box::into_raw(memdb.into_boxed_slice()) as *mut u8)
});
```